Graphical CSS Code Transformation Using ZX Calculus

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In this work, we present a generic approach to transform CSS codes by building upon their equivalence to phase-free ZX diagrams. Using the ZX calculus, we demonstrate diagrammatic transformations between encoding maps associated with different codes. As a motivating example, we give explicit transformations between the Steane code and the quantum Reed-Muller code, since by switching between these two codes, one can obtain a fault-tolerant universal gate set. To this end, we propose a bidirectional rewrite rule to find a (not necessarily transversal) physical implementation for any logical ZX diagram in any CSS code.

We then focus on two code transformation techniques: *code morphing*, a procedure that transforms a code while retaining its fault-tolerant gates, and *gauge fixing*, where complimentary codes can be obtained from a common subsystem code (e.g., the Steane and the quantum Reed-Muller codes from the [15,1,3,3] code). We provide explicit graphical derivations for these techniques and show how ZX and graphical encoder maps relate several equivalent perspectives on these code transforming operations.

1 Introduction

Quantum computation has demonstrated its potential in speeding up large-scale computational tasks [3, 68] and revolutionizing multidisciplinary fields such as drug discovery [11], climate prediction [60], chemistry simulation [47], and the quantum internet [25]. However, in a quantum system, qubits are sensitive to interference and information becomes degraded [50]. To this end, quantum error correction [55, 57] and fault tolerance [33, 41] have been developed to achieve large-scale universal quantum computation [34].

Stabilizer theory [32] is a mathematical framework to describe and analyze properties of quantum error-correcting codes (QECC). It is based on the concept of stabilizer groups, which are groups of Pauli operators whose joint +1 eigenspace corresponds to the code space. Stabilizer codes are a specific type of QECC whose encoder can be efficiently simulated [1, 31]. As a family of stabilizer codes, Calderbank-Shor-Steane (CSS) codes permit simple code constructions from classical codes [9, 10, 57, 58].

As a language for rigorous diagrammatic reasoning of quantum computation, the ZX calculus consists of ZX diagrams and a set of rewrite rules [16, 66]. It has been used to relate stabilizer theory to graphical normal forms: notably, efficient axiomatization of the stabilizer fragments for qubits [4, 36, 49],

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qutrits [61, 65], and prime-dimensional qudits [8]. This has enabled various applications, such as measurement-based quantum computation [49, 56], quantum circuit optimization [19, 30] and verification [46], as well as classical simulation [14, 40]. Beyond these, ZX-calculus has been applied to verify QECC [23, 26], represent Clifford encoders [38], as well as study various QECC such as tripartite coherent parity check codes [12, 13] and surface codes [27, 28, 29, 54]. Specific to CSS codes, ZX-calculus has been used to visualize their encoders [39], code maps and code surgeries [22], their correspondence to affine Lagrangian relations [20], and their constructions in high-dimensional quantum systems [21].

In this paper, we seek to answer some overarching questions about QECC constructions and fault-tolerant implementations. We focus on CSS codes and leverage the direct correspondence between phase-free ZX diagrams and CSS code encoders [39]. Given an arbitrary CSS code, based on its normal form, we propose a bidirectional rewrite rule to find a (not necessarily transversal) physical implementation for any logical ZX diagram. Furthermore, we demonstrate diagrammatic transformations between encoding maps associated with different codes. Here, we focus on two code transformation techniques: *code morphing*, a procedure that transforms a code while retaining its fault-tolerant gates [62], and *gauge fixing*, where complimentary codes (such as the Steane and the quantum Reed-Muller codes) can be obtained from a common subsystem code [2, 51, 53, 64]. We provide explicit graphical derivations for these techniques and show how ZX and graphical encoder maps relate several equivalent perspectives on these code transforming operations.

The rest of this paper is organized as follows. In Sec. 2, we introduce notions and techniques used to graphically transform different CSS codes using the ZX calculus. In Sec. 3, we generalize the ZX normal form for CSS stabilizer codes to CSS subsystem codes, and provide generic bidirectional rewrite rules for any CSS encoder. In Sec. 4, we provide explicit graphical derivations for morphing the Steane and the quantum Reed-Muller codes. In Sec. 5, we focus on the switching protocol between these two codes. Through ZX calculus, we provide a graphical interpretation of this protocol as gauge fixing the [15,1,3,3] subsystem code, followed by syndrome-determined recovery operations. We conclude with Sec. 6.

2 Preliminaries

We start with some definitions. The Pauli matrices are 2×2 unitary operators acting on a single qubit. Let *i* be the imaginary unit.

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \quad Y = iXZ = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}.$$

Let \mathcal{P}_1 be the single-qubit Pauli group, $\mathcal{P}_1 = \langle i, X, Z \rangle$, $I, Y \in \mathcal{P}_1$.

Definition 2.1. Let $U \in \mathcal{U}(2)$. In a system over n qubits, $1 \le i \le n$,

$$U_i = I \otimes \ldots \otimes I \otimes U \otimes I \otimes \ldots \otimes I$$

denotes U acting on the i-th qubit, and identity on all other qubits.

Let \mathcal{P}_n be the *n*-qubit Pauli group. It consists of all tensor products of single-qubit Pauli operators.

$$\mathcal{P}_n = \langle i, X_1, Z_1, \dots, X_n, Z_n \rangle.$$

The stabilizer formalism is a mathematical framework to describe and analyze the properties of certain QECC, called stabilizer codes [32, 33]. Consider n qubits and let $m \le n$. A stabilizer group $S = \langle S_1, \ldots, S_m \rangle$ is an Abelian subgroup of \mathcal{P}_n that does not contain -I. The codespace of the corresponding stabilizer code, C, is the joint +1 eigenspace of S, i.e.,

$$C = \{ |\psi\rangle \in \mathbb{C}^{2^n}; \ S|\psi\rangle = |\psi\rangle, \forall S \in \mathcal{S} \}.$$

The number of encoded qubits in a stabilizer code is k = n - m, where m is the number of independent stabilizer generators [32]. Moreover, we can define the *centralizer* of S as

$$\mathcal{N}(\mathcal{S}) = \{ U \in \mathcal{P}_n; \ [U, S] = 0, \forall S \in \mathcal{S} \}.$$

One can check that $\mathcal{N}(\mathcal{S})$ is a subgroup of \mathcal{P}_n and $\mathcal{S} \subset \mathcal{N}(\mathcal{S})$. We remark that the notions of normalizer and centralizer coincide for any stabilizer group. In what follows, we will use them interchangeably. As we will see later, $\mathcal{N}(\mathcal{S})$ provides an algebraic structure for the subsystem codes. The code distance, d, of a stabilizer code is the minimal weight of operators in $\mathcal{N}(\mathcal{S})/\langle iI \rangle$ that is not in \mathcal{S} . We summarize the properties of a stabilizer code with the shorthand [n,k,d].

Finally, we introduce some notation for subsets of *n*-qubit Pauli operators, which will prove useful for defining CSS codes.

Definition 2.2. Let M be an $m \times n$ binary matrix and $Q \in \mathcal{P}_1/\langle iI \rangle$. In the stabilizer formalism, M is called the stabilizer matrix, and M^Q defines m Q-type stabilizer generators.

$$M^{\mathcal{Q}} := \left\{ \bigotimes_{j=1}^{n} \mathcal{Q}^{[M]_{ij}}; \ 1 \leq i \leq m \right\}.$$

CSS codes are QECC whose stabilizers are defined by two orthogonal binary matrices G and H [9, 57]:

$$S = \langle G^X, H^Z \rangle, \quad GH^{\mathsf{T}} = \mathbf{0},$$

 H^{\dagger} is the transpose of H. This means that the stabilizer generators of a CSS code can be divided into two types: X-type and Z-type. For example, the [7,1,3] Steane code [57] in Fig. 1a is specified by

$$G = H = \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 \end{bmatrix}_{3 \times 7}.$$
 (1)

Accordingly, the X-type and Z-type stabilizers are defined as

$$S_1^X = X_1 X_3 X_5 X_7, \ S_2^X = X_2 X_3 X_6 X_7, \ S_3^X = X_4 X_5 X_6 X_7, \ S_1^Z = Z_1 Z_3 Z_5 Z_7, \ S_2^Z = Z_2 Z_3 Z_6 Z_7, \ S_3^Z = Z_4 Z_5 Z_6 Z_7.$$

The logical operators \overline{X} and \overline{Z} are defined as

$$\overline{X} = X_1 X_4 X_5$$
 and $\overline{Z} = Z_1 Z_4 Z_5$. (2)

In Sec. 2.1, we define CSS subsystem codes. In Sec. 2.2, we define several CSS codes that will be used in subsequent sections. In Sec. 2.3, we introduce the basics of the ZX calculus and the phase-free ZX normal forms.

2.1 CSS Subsystem Codes

Subsystem codes [43, 52] are QECC where some of the logical qubits are not used for information storage and processing. These logical qubits are called gauge qubits. By fixing gauge qubits to some specific states, the same subsystem code may exhibit different properties, for instance, having different sets of transversal gates [7, 44, 45, 51, 67]. This provides a tool to circumvent restrictions on transversal gates such as the Eastin-Knill theorem [24].

Based on the construction proposed in [52], we describe a subsystem code using the stabilizer formalism.

Definition 2.3. Given a stabilizer group S, a gauge group G is a normal subgroup of N(S), such that $S \subset G$ and that G/S contains anticommuting Pauli pairs. In other words, one can write

$$S = \langle S_1, \dots, S_m \rangle, \quad G = \langle S_1, \dots, S_m, g_1^X, g_1^Z, \dots, g_r^X, g_r^Z \rangle, \quad 1 \le m + r \le n.$$

(S,G) defines an [n,k,r,d] subsystem code where n=m+k+r. The logical operators are elements of the quotient group $\mathcal{L} = \mathcal{N}(S)/\mathcal{G}$.

Under this construction, n physical qubits are used to encode k logical qubits with r gauge qubits. Alternatively, we can think of the gauge group \mathcal{G} as partitioning the code space \mathcal{C} into two subsystems: $\mathcal{C} = \mathcal{A} \otimes \mathcal{B}$. Logical information is encoded in \mathcal{A} and \mathcal{L} serves as the group of logical operations. Gauge operators from \mathcal{G} act trivially on subsystem \mathcal{A} , while operators from \mathcal{L} act trivially on subsystem \mathcal{B} . Therefore, two states $\rho^{\mathcal{A}} \otimes \rho^{\mathcal{B}}$ and $\rho'^{\mathcal{A}} \otimes \rho'^{\mathcal{B}}$ are considered equivalent if $\rho^{\mathcal{A}} = \rho'^{\mathcal{A}}$, regardless of the states $\rho^{\mathcal{B}}$ and $\rho'^{\mathcal{B}}$. When r = 0, $\mathcal{G} = \mathcal{S}$. In that case, an [n,k,0,d] subsystem code is essentially an [n,k,d] stabilizer code.

CSS subsystem codes are subsystem codes whose stabilizer generators can be divided into X-type and Z-type operators. In what follows, we provide an example to illustrate their construction.

2.2 Some Interesting CSS Codes

We start by defining the stabilizer groups for the [7,1,3] Steane code, the [15,1,3] extended Steane code [2], and the [15,1,3] quantum Reed-Muller code [42]. They are derived from the family of $[2^m - 1,1,3]$ quantum Reed-Muller codes, with a recursive construction of stabilizer matrices [59]. The Steane code has transversal logical Clifford operators, and the quantum Reed-Muller code has a transversal logical T gate. Together these operators form a universal set of fault-tolerant gates. In Sec. 5, the relations between these codes are studied from a diagrammatic perspective.

For brevity, their corresponding stabilizer groups are denoted as S_{steane} , S_{ex} , and S_{qrm} . As per Def. 2.2, consider three stabilizer matrices F, H, and J. Note that G is defined in Eq. (1). $\mathbf{0}$ and $\mathbf{1}$ denote blocks of 0s' and 1s' respectively. Their dimensions can be inferred from the context.

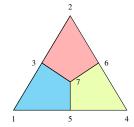
Then, the stabilizer groups are defined as

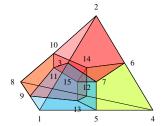
$$S_{steane} = \langle G^X, G^Z \rangle, \quad S_{ex} = \langle F^X, F^Z, H^X, H^Z \rangle, \quad S_{grm} = \langle F^X, F^Z, H^Z, J^Z \rangle.$$
 (3)

Geometrically, one can define S_{steane} and S_{qrm} with the aid of Fig. 1. In Fig. 1a, the Steane code is visualized on a 2D lattice. Since the Steane code is self-dual, every coloured face corresponds to an X-type and Z-type stabilizer. In Fig. 1b, the quantum Reed-Muller code is visualized on a 3D lattice. Every coloured face corresponds to a weight-4 Z-type stabilizer. Every coloured cell corresponds to a weight-8 X-type stabilizer. For the Steane code, the logical operators defined in Eq. (2) correspond to an edge in Fig. 1a. For the quantum Reed-Muller code, the logical operators (defined below) correspond to a triangular face in Fig. 1b.

$$\overline{X} = X_1 X_2 X_3 X_4 X_5 X_6 X_7$$
 and $\overline{Z} = Z_1 Z_2 Z_3 Z_4 Z_5 Z_6 Z_7$. (4)

Given such representations, the Steane code and the quantum Reed-Muller code are also special cases of colour codes [5, 6, 44].





- (a) The Steane code as a 2D colour code.
- (b) The quantum Reed-Muller as a 3D colour code.

Figure 1: Each vertex represents a physical qubit. Each edge serves as an aid to the eye. They do not imply any physical interactions or inherent structures.

From Eq. (3), the extended Steane code is self-dual, and its encoded state is characterized by the lemma below. It shows that S_{ex} and S_{steane} are equivalent up to some auxiliary state.

Lemma 2.1 ([2]). Any codeword $|\psi\rangle$ of the extended Steane code can be decomposed into a codeword $|\phi\rangle$ of the Steane code and a fixed state $|\eta\rangle$. That is,

$$|\psi\rangle = |\phi\rangle \otimes |\eta\rangle,$$

where $|\eta\rangle = \frac{1}{\sqrt{2}}(|0\rangle|\overline{0}\rangle + |1\rangle|\overline{1}\rangle)$, $|\overline{0}\rangle$ and $|\overline{1}\rangle$ are the logical 0 and 1 encoded in the Steane code.

Since the logical information $|\phi\rangle$ encoded in the Steane code is not entangled with $|\eta\rangle$, to switch between the Steane code and the extended Steane code, one may simply add or discard the auxiliary state $|\eta\rangle$. This property will prove useful in Sec. 5.

Next, we define the [15,1,3,3] CSS subsystem code [64]. As per Def. 2.3, let S_{sub} and G be its stabilizer group and gauge group respectively.

$$S_{sub} = \langle F^X, F^Z, H^Z \rangle, \quad \mathcal{G} = \langle F^X, F^Z, H^X, H^Z, J^Z \rangle. \tag{5}$$

Let $\mathcal{L}_g = \mathcal{G}/\mathcal{S}$ and $\mathcal{L} = \mathcal{N}(\mathcal{S})/\mathcal{G}$. One can verify that

$$\mathcal{L}_g = \langle H^X, J^Z \rangle, \quad \mathcal{L} = \langle \overline{X}, \overline{Z} \rangle.$$
 (6)

Thus, the CSS subsystem code has one logical qubit and three gauge qubits, and they are acted on by \mathcal{L}_g and \mathcal{L} respectively. From Sec. 3 onwards, we call operators in \mathcal{L}_g as *gauge operators*.

Moreover, S_{sub} can be viewed as the stabilizer group of a [15,4,3] CSS code, with logical operators \mathcal{L}' . This code appears in an intermediary step of the gauge fixing process in Sec. 5.

$$\mathcal{L}' := \mathcal{L}_g \cup \mathcal{L} = \langle H^X, J^Z, \overline{X}, \overline{Z} \rangle. \tag{7}$$

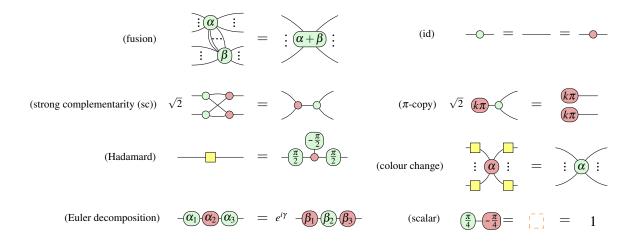


Figure 2: These eight equations suffice to derive all other equalities of linear maps on qubits [63]. $k \in \mathbb{Z}_2$. α_i , β_i and γ are real numbers satisfying the trigonometric relations derived in [18]. Each equation still holds when we replace all spiders with their corresponding spiders of the opposite colour. Whenever there are any two wires with ... between them, the rule holds when replacing this with any number of wires (i.e., 0 or greater).

2.3 ZX Calculus

The qubit ZX-calculus [15, 16, 17, 66] is a quantum graphical calculus for diagrammatic reasoning of any qubit quantum computation. Every diagram in the calculus is composed of two types of generators: Z spiders, which sum over the eigenbasis of the Pauli Z operator:

$${}^{m}\left\langle \begin{array}{c} \vdots \alpha \right\rangle \vdots \left\rangle {}^{n} := \left| 0 \right\rangle {}^{\otimes n} \left\langle 0 \right| {}^{\otimes m} + e^{i\alpha} |1\rangle {}^{\otimes n} \left\langle 1 \right| {}^{\otimes m}, \tag{8}$$

and X spiders, which sum over the eigenbasis of the Pauli X operator:

$${}^{m}\langle \vdots \alpha \vdots \rangle_{n} := |+\rangle^{\otimes n}\langle +|^{\otimes m} + e^{i\alpha}|-\rangle^{\otimes n}\langle -|^{\otimes m}. \tag{9}$$

The ZX-calculus is *universal* [16] in the sense that any linear map from m qubits to n qubits corresponds exactly to a ZX diagram, by the construction of Eqs. (8) and (9) and the composition of linear maps.

Furthermore, the ZX-calculus is *complete* [35, 37]: Any equality of linear maps on any number of qubits derivable in the Hilbert space formalism, is derivable using only a finite set of rules in the calculus. The smallest complete rule set to date [63] is shown in Fig. 2. Some additional rules, despite being derivable from this rule set, will be convenient to use in this paper. They are summarized in Fig. 3.

When a spider has phase zero, we omit its phase in the diagram, as shown below. A ZX diagram is *phase-free* if all of its spiders have zero phases. For more discussions on phase-free ZX diagrams, we refer readers to consult [39].

Due to the universality of the ZX calculus, quantum error-correcting code encoders, as linear isometries, can be drawn as ZX diagrams [38]. Moreover, the encoder for a CSS code corresponds exactly to the phase-free ZX (and XZ) normal form [39].

Definition 2.4. For a CSS stabilizer code defined by S, let $\{S_i^x; 1 \le i \le m\} \subset S$ be the X-type stabilizer generators and $\{\overline{X_j}; 1 \le j \le k\}$ be the logical X operators, m+k < n. Its ZX normal form can be found via the following steps:

- (a) For each physical qubit, introduce an X spider.
- (b) For each X-type stabilizer generator S_i^x and logical operator $\overline{X_j}$, introduce a Z spider and connect it to all X spiders where this operator has support.
- (c) Give each X spider an output wire.
- (d) For each Z spider representing $\overline{X_i}$, give it an input wire.

As an example, the ZX normal form for the Steane code is drawn in Fig. 4. The XZ normal form can be constructed based on Z-type stabilizer generators and logical Z operators by inverting the roles of X and Z spiders in the above procedure. In [39], Kissinger gave an algorithm to rewrite any phase-free ZX diagram into both the ZX and XZ normal forms, and pointed out that it is sufficient to represent a CSS code encoder using either one of the forms.

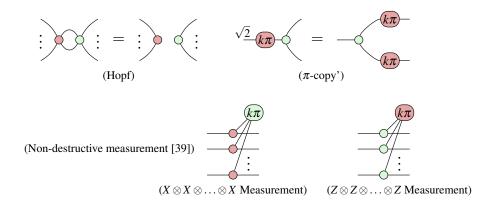


Figure 3: Some other useful rewrite rules, each derivable from the rules in Figure 2. $k \in \mathbb{Z}_2$. Each equation still holds when we interchange X and Z spiders.

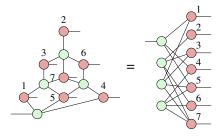


Figure 4: The Steane code encoder in the ZX normal form.

3 Graphical Construction of CSS Encoders

3.1 ZX Normal Forms for CSS Subsystem Codes

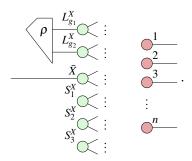
We generalize the ZX normal form for CSS stabilizer codes to CSS subsystem codes as follows.

Definition 3.1. For an [n,k,r,d] CSS subsystem code defined by (S,G), let $\{S_i^x; 1 \le i \le m\}$ be the X-type stabilizer generators, $\{L_{g_t}^x; 1 \le t \le r\}$ be the X-type gauge operators, and $\{\overline{X_j}; 1 \le j \le k\}$ be the logical X operators, m+k+r < n. Its ZX normal form can be found via the following steps:

- (a) For each physical qubit, introduce an X spider.
- (b) For each stabilizer generator S_i^x , logical operator $\overline{X_j}$ and gauge operator $L_{g_i}^x$, introduce a Z spider and connect it to all X spiders where this operator has support.
- (c) Give each X spider an output wire.
- (d) For each Z spider representing $\overline{X_i}$, give it an input wire.
- (e) For all Z spiders representing $L_{g_t}^{x}$, attach to them a joint arbitrary input state (i.e., a density operator ρ).

Similar to CSS stabilizer codes, CSS subsystem codes also have an equivalent XZ normal form, which can be found by inverting the role of Z and X in the above procedure.

For n > 3, below we exemplify the ZX normal form for an [n, 1, 2, d] CSS subsystem code with three X-type stabilizers generators $\{S_1^x, S_2^x, S_3^x\}$, two X-type gauge operators $\{L_{g_1}^x, L_{g_2}^x\}$, and one logical operator $\{\overline{X}\}$. For simplicity, we substitute wires connecting Z and X spiders by \subseteq : The detailed connectivities are omitted here, but they should be clear following step (b) in Def. 3.1. This notation will be used in the remainder of this paper.



3.2 Pushing through the Encoder

For any [n, k, d] CSS code, its encoder map E is of the form:

$$k\left\{\begin{array}{c|c} \hline \vdots & E & \vdots \\ \hline \end{array}\right\}n.$$

Definition 3.2. Let $\overline{X_i}$ and $\overline{Z_i}$ be the X and Z operators acting on the i-th logical qubit. Let $\overline{X_i}$ and $\overline{Z_i}$ be the physical implementation of $\overline{X_i}$ and $\overline{Z_i}$ respectively. Diagrammatically, they can be represented as

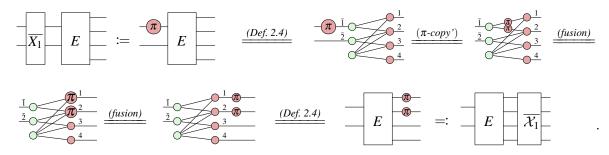
In other words, pushing $\overline{X_i}$ (or $\overline{Z_i}$) through E yields $\overline{X_i}$ (or $\overline{Z_i}$). Using ZX rewrite rules along with the ZX (or XZ) normal form, we can prove the following lemma.

Lemma 3.1. For any CSS code, all $\overline{X_i}$ and $\overline{Z_i}$ are implementable by multiple single-qubit Pauli operators. In other words, all CSS codes have transversal $\overline{X_i}$ and $\overline{Z_i}$.

Proof. Consider an arbitrary CSS code. Without loss of generality, represent its encoder E in the ZX normal form following Def. 2.4. Then proceed by applying the π -copy' rule on every $\overline{X_i}$ (the X spider with a phase π on the left-hand side of the encoder E).

Below we illustrate the proof using the [4,2,2] code as an example.

Example 3.1. For the [4,2,2] code, $\overline{X_1} = X_1X_2$.



Beyond just X or Z spiders, one can push *any* ZX diagram acting on the logical qubits through the encoder. Such pushing is bidirectional, and the left-to-right direction is interpreted as finding a physical implementation for a given logical operator.

Proposition 3.1. Let E be the encoder of a CSS code. For any ZX diagram E on the left-hand side of E, one can write down a corresponding ZX diagram E on the right-hand side of E, such that EL = PE. In other words, E is a valid physical implementation of E for that CSS code.

Proof. We proceed as follows. First, unfuse all spiders on the logical qubit wires of L, whenever they are not phase-free or have more than one external wire:

For each X (or Z) spider on the logical qubit wire, rewriting E to be in ZX (or XZ) normal form and applying the strong complementarity (sc) rule yields:

On the left-hand side, a phase-free X (or Z) spider acts on the *i*-th logical qubit; on the righthand side, phase-free X (or Z) spiders act on all physical qubits wherever \overline{X}_i (or \overline{Z}_i) has support. Therefore, any type of L can be pushed through E, resulting in a diagram P which satisfies EL = PE.

In [26], it was proved that a physical implementation P of a logical operator L satisfies $L = E^{\dagger}PE$. This is implied by EL = PE as $E^{\dagger}E = I$.

4 Graphical Morphing of CSS Codes

One way to transform CSS codes is known as *code morphing* [62]. It provides a systematic framework to construct new codes from an existing code, while preserving the number of logical qubits in the morphed code. Here, we present this procedure through the rewrites of the encoder diagram using the ZX calculus. Let us start by revisiting the code morphing definition in [62].

Definition 4.1. Let S be a stabilizer group and C be its joint +1 eigenspace. C is called the parent code. Let Q denote the set of physical qubits of C and $R \subseteq Q$. Then S(R) is a subgroup of S generated by all stabilizers of S that are fully supported on S. Let C(R) be the joint S eigenspace of S(R), and S is called the child code. Given the parent code encoder S concatenate it with the inverse of the child code encoder S is gives the morphed code S encoder S is gives the morphed code S is S encoder S in S eigenspace. S is a subgroup of S generated by all stabilizers of S that are fully supported on S encoder S encoder S is a subgroup of S generated by all stabilizers of S that are fully supported on S encoder S encoder

Fig. 5 provides two equivalent interpretations for the code morphing process. In Fig. 5a, Def. 4.1 is depicted by the circuit diagram. Note that as $E_{\mathcal{C}(R)}$ is an isometry, $E_{\mathcal{C}(R)}^{\dagger}E_{\mathcal{C}(R)}=I$. By construction, the equation shown in Fig. 5a holds [62]. Moreover, the parameters of $\mathcal{C}=[n,k,d]$, $\mathcal{C}(R)=[n_1,k_1,d_1]$, and $\mathcal{C}_{\backslash R}=[n_2,k_2,d_2]$ are characterized below. Let m,m_1,m_2 be the number of stabilizer generators for \mathcal{C} , $\mathcal{C}(R)$, and $\mathcal{C}_{\backslash R}$ respectively. Then

$$n_2 = n - n_1 + k_1$$
, $k_2 = k$, $m_2 = (n - k) - (n_1 - k_1) = m - m_1$, $d_1, d_2 \in \mathbb{N}$.

Fig. 5b provides a concrete example of applying Def. 4.1 to the $[\![7,1,3]\!]$ Steane code, where $S=\{1,2,3,4,5,6,7\}$ and $R=\{2,3,6,7\}$. As a result, the $[\![5,1,2]\!]$ code is morphed from the parent code along with the $[\![4,2,2]\!]$ child code. This morphed code inherits a fault-tolerant implementation of the Clifford group from the $[\![7,1,3]\!]$ code, which has a transversal implementation of the Clifford group. This morphing process is represented in the ZX diagram by cutting the edges labelled by $\overline{1}$ and $\overline{2}$ adjacent to the X spider. This is equivalent to concatenating the ZX diagram of $E_{[\![4,2,2]\!]}^{\dagger}$ in Fig. 5a.

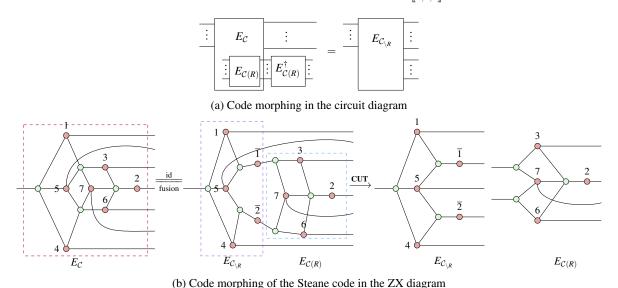


Figure 5: Code morphing can be visualized using both circuit and ZX diagrams. In Fig. 5a, code morphing is viewed as a concatenation of the parent code encoder $E_{\mathcal{C}}$ and the inverse of the child code encoder $E_{\mathcal{C}(R)}$. In Fig. 5b, the encoder $E_{\mathcal{C}}$ of the Steane code is represented in the ZX normal form. As described in Proc. 4.1, by applying ZX rules (id) and (fusion) in Fig. 2, we can perform code morphing by bipartitioning it into the encoder $E_{\mathcal{C}\setminus R}$ of the morphed code $\mathcal{C}_{\setminus R} = [\![5,1,2]\!]$, and the encoder $E_{\mathcal{C}(R)}$ of the child code $\mathcal{C}(R) = [\![4,2,2]\!]$.

Next, we generalize the notion of code morphing and show how ZX calculus could be used to study these relations between the encoders of different CSS codes. More precisely, we provide an algorithm to morph a new CSS code from an existing CSS code.

Procedure 4.1. Given a parent code C and a child code C(R) satisfying Def. 4.1, construct the encoder of C in the ZX normal form. Then the code morphing proceeds as follows:

- (a) Unfuse every Z spider which is supported on c qubits within R and f qubits outside R, $c \neq 0$, $f \neq 0$.
- (b) Add an identity X spider between each pair of Z spiders being unfused in step (a).
- (c) Cut the edge between this X spider and the Z spider supported on the f qubits in R.

It follows that the subdiagram containing R corresponds to the ZX normal form of $E_{\mathcal{C}(R)}$. It has the same number of X spiders as R, so $n_1 = |R|$. Suppose that there are h Z spiders being unfused. Then h must be bounded by the number of Z spiders in the ZX normal form of $E_{\mathcal{C}}$. As each spider unfusion introduces a logical qubit to $\mathcal{C}(R)$, $k_1 = h$. On the other hand, the complement subdiagram contains $n - n_1 + k_1$ X spiders as each edge cut introduces a new X spider into the complement subdiagram. It also contains k logical qubits as the input edges in the ZX normal form of $E_{\mathcal{C}}$ are invariant throughout the spider-unfusing and edge-cutting process. This gives the ZX normal form for the encoder of the morphed code $\mathcal{C}_{\backslash \mathcal{R}} = [n_2, k_2, d_2]$, where $n_2 = n - n_1 + k_1$, $k_2 = k$, $k_3 = k$. As a result, the ZX normal form of $k_3 = k$ 0 is decomposed into the ZX normal forms of $k_3 = k$ 1.

As the XZ and ZX normal forms are equivalent for CSS codes, Proc. 4.1 can be carried out for the XZ normal form by inverting the roles of Z and X at each step.

Here, we exemplify the application of Proc. 4.1 by morphing two simple CSS codes. Unlike Fig. 5b, Ex. 4.1 chooses a different subset of qubits, $R = \{4,5,6,7\}$, to obtain the [6,1,1] morphed code. In Ex. 4.2, we visualize the morphing of the [10,1,2] code from the [15,1,3] quantum Reed-Muller code. The [10,1,2] code is interesting because it inherits a fault-tolerant implementation of the logical T gate from its parent code, which has a transversal implementation of the logical T gate. In fact, the [10,1,2] code is the smallest known code with a fault-tolerant T gate.

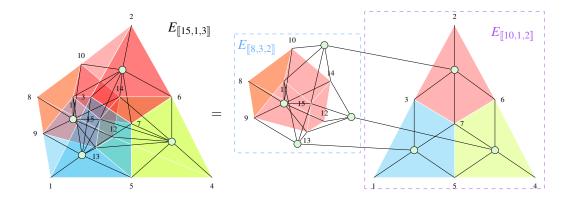
Example 4.1. Let the Steane code be the parent code and the [4,3,1] code be the child code. By Proc. 4.1, we obtain the [6,1,1] morphed code. Note that for the child code, there is precisely one X-type stabilizer generator and no Z-type stabilizer generator. This means that the [4,3,1] code cannot detect a single-qubit X error, so it has distance 1. In the morphed code, the physical qubit labelled $\overline{3}$ is not protected by any X-type stabilizer. Therefore, the [6,1,1] code is of distance 1.

$$E_{\llbracket 7,1,3\rrbracket}$$

$$E_{\llbracket 6,1,1\rrbracket}$$

$$E_{\llbracket 4,3,1\rrbracket}$$

Example 4.2. Let the quantum Reed-Muller code be the parent code and the [8,3,2] code be the child code. By Proc. 4.1, we obtain the [10,1,2] morphed code. For brevity, the X spiders representing physical qubits and the logical qubit wires inputting to the Z spiders are omitted.



5 Graphical Code Switching of CSS Codes

Another way to transform CSS codes is known as *code switching*. It is a widely studied technique in quantum error correction. Codes with complementary fault-tolerant gate sets are switched between each other to realize a universal set of logical operations. As a case study, we focus on the code switching protocol between the Steane code and the quantum Reed-Muller code [2, 51, 53]. Since this process is bidirectional, the reasoning for one direction can be simply adjusted for the opposite direction. Recall in Lem. 2.1, we showed that the extended Steane code is equivalent to the Steane code up to some auxiliary state. In what follows, we focus on the *backward switching* from the quantum Reed-Muller code to the extended Steane code.

Using the ZX calculus, we provide a graphical interpretation for the backward code switching. More precisely, it is visualized as gauge fixing the [15,1,3,3] subsystem code, along with a sequence of syndrome-determined recovery operations.

We first characterize the relations between the quantum Reed-Muller code, the extended Steane code, and the [15, 1, 3, 3] subsystem code. For brevity, we denote these codes as C_{qrm} , C_{ex} and C_{sub} , and their respective encoders as E_{qrm} , E_{ex} , and E_{sub} .

Lemma 5.1. When the three gauge qubits are in the $|+++\rangle$ state, C_{sub} is equal to C_{ex} , as shown in Fig. 6.

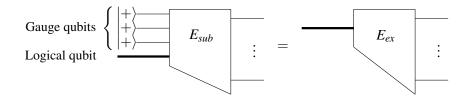
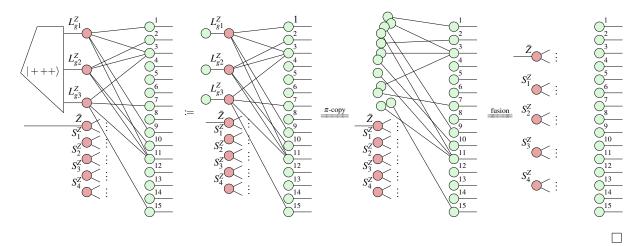


Figure 6: C_{sub} is equivalent to C_{ex} up to a fixed state of gauge qubits.

Proof. By Def. 3.1, E_{sub} in the XZ normal form is shown below. Using a sequence of ZX rewrite rules, we obtain exactly the XZ normal form for E_{ex} which captures both the Z-type stabilizer generators S_i^z

and Z logical operators $L_{g_i}^Z$.



If E_{sub} is represented in the ZX normal form, the Z spider of each gauge qubit in the $|\mp\rangle$ state will fuse with its gauge logical X operator $L_{g_i}^X$. This yields an X-type stabilizer generator S_i^X of C_{ex} with the same support as $L_{g_i}^X$.

Corollary 5.1. Likewise, when the three gauge qubits are in the $|\overline{000}\rangle$ state, C_{sub} is equal to C_{qrm} .

In [2, 51], code switching is described as a *gauge fixing* process. Further afield, [64] provides a generic recipe to gauge fix a CSS subsystem code. Here, we generalize Lem. 5.1 and describe how to gauge fix C_{sub} to C_{ex} through the lens of ZX calculus.

Proposition 5.2. Gauge fixing C_{sub} in the following steps results in C_{ex} , as shown in Fig. 7.

- (a) Measure three X-type gauge operators $L_{g_i}^X$ and obtain the corresponding outcomes $k_1, k_2, k_3 \in \mathbb{Z}_2$.
- (b) When $k_i = 1$, the gauge qubit i has collapsed to the wrong state $|\overline{-}\rangle$. Apply the Z-type recovery operation $L_{g_i}^Z$.

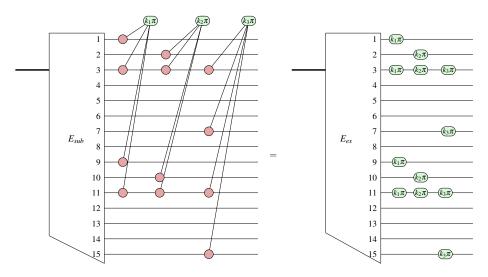
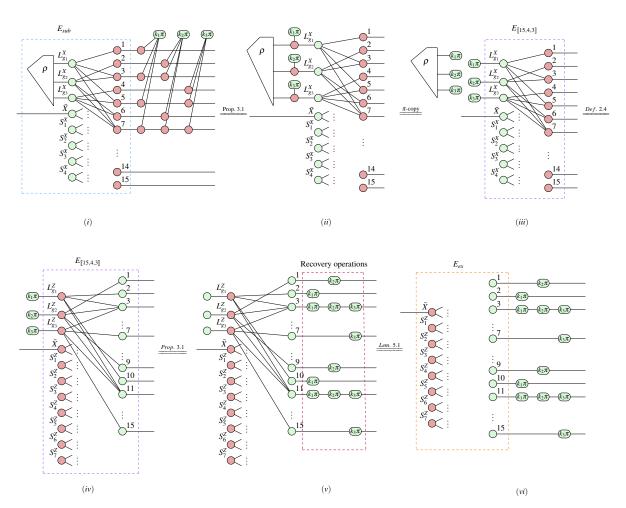


Figure 7: Gauge fixing C_{sub} to C_{ex} in the circuit diagram.

Proof. By Def. 3.1, construct the ZX normal form of E_{sub} in the blue dashed box of (i). Then the three gauge operators $L_{g_i}^X$ are measured in step (a). The subsequent equalities follow from Figs. 2 and 3. Next, we observe that the purple dashed box in (iii) is exactly the encoder of the [15,4,3] stabilizer code. By Lemma 3.2 in [39], it can be equivalently expressed in the XZ normal form, as in (iv). By Prop. 3.1, pushing each Z spider with the phase $k_i\pi$ across $E_{[15,4,3]}$ results in (v). In step (b), Pauli Z operators are applied based upon the measurement outcome k_i , which corresponds to the recovery operations in the red dashed box of (v). After that, the gauge qubits of C_{sub} are set to the $|\overline{+++}\rangle$ state. By Lem. 5.1, we obtain the XZ normal form for E_{ex} , as shown in the orange dashed box of (vi). Therefore, the equation in Fig. 7 holds.



We sum up by explaining how to obtain \mathcal{C}_{ex} and \mathcal{C}_{qrm} by gauge fixing \mathcal{C}_{sub} . In Prop. 5.2, we showed that measuring the gauge operators $L_{g_i}^X$ followed by the recovery Z-type operations $L_{g_i}^Z$ is equivalent to adding $L_{g_i}^X$ to the stabilizer group \mathcal{S}_{sub} . This results in the formation of \mathcal{C}_{ex} . Analogously, measuring the gauge operators $L_{g_i}^Z$ followed by the recovery X-type operations $L_{g_i}^X$ is equivalent to adding $L_{g_i}^Z$ to \mathcal{S}_{sub} . Thus, we obtain \mathcal{C}_{arm} .

Alternatively, gauge fixing C_{sub} can be viewed as a way of switching between C_{ex} and C_{qrm} [2, 53]. As an example, in Fig. 8, we visualize the measurement of $L_{g_1}^X := X_1 X_3 X_5 X_7$ in order to switch from C_{qrm} to C_{ex} . The effect of measuring other X-type gauge operators can be reasoned analogously. In

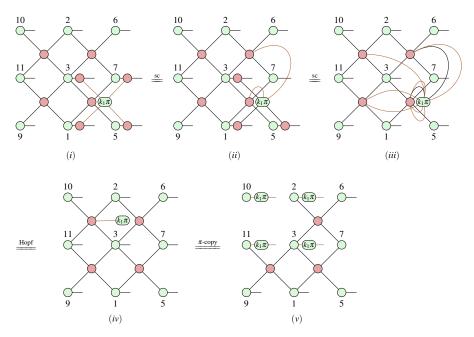


Figure 8: The switching from C_{qrm} to C_{ex} provides an alternative interpretation of Prop. 5.2. After measuring $L_{g_1}^X$, is removed from the stabilizer group S_{qrm} and the recovery operation is performed based on the measurement syndrome. Note that unrelated X and Z spiders are omitted from the ZX diagrams.

(i), the encoder of \mathcal{C}_{qrm} is represented in the XZ normal form and $L^X_{g_1}$ is measured. After applying a sequence of ZX rewrite rules, in (v) the stabilizer $L^Z_{g_1} \coloneqq Z_2 Z_3 Z_{10} Z_{11}$ is removed from the stabilizer group \mathcal{S}_{qrm} of \mathcal{C}_{qrm} . Moreover, the recovery operations can be read off from the graphical derivation: $(Z_2 Z_3 Z_{10} Z_{11})^{k_1} = (L^Z_{g_1})^{k_1}$, $k_1 \in \mathbb{Z}_2$.

Overall, ZX visualization provides a deeper understanding of the gauge fixing and code switching protocols. On top of revealing the relations between different CSS codes' encoders, it may provide a simple yet rigorous test for various fault-tolerant protocols. Beyond this, it will serve as an intuitive guiding principle for the implementation of various logical operations.

6 Conclusion

In this paper, we generalize the notions in [39] and describe a normal form for CSS subsystem codes. Built upon the equivalence between CSS codes and the phase-free ZX diagrams, we provide a bidirectional rewrite rule to establish a correspondence between a logical ZX diagram and its physical implementation. With these tools in place, we provide a graphical representation of two code transformation techniques: code morphing, a procedure that transforms a code through unfusing spiders for the stabilizer generators, and gauge fixing, where different stabilizer codes can be obtained from a common subsystem code. These explicit graphical derivations show how the ZX calculus and graphical encoder maps relate several equivalent perspectives on these code transforming operations, allowing potential utilities of ZX to simplify fault-tolerant protocols and verify their correctness.

Looking ahead, many questions remain. It is still not clear how to present the general code deformation of CSS codes using phase-free ZX diagrams. Besides, understanding code concatenation through the lens of ZX calculus may help derive new and better codes. In addition, it would be interesting to look at other code modification techniques derived from the classical coding theory [48].

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